Integrable field theories with defects

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July 2010

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Integrable dynamical systems and field theory have a long history (over 100 years) - with many developments since 1968.

Integrable field theory in the presence of boundaries (one boundary or two), or defects (shocks), is more recent.

The purpose here is to give (from a personal perspective) a small collection of ideas and questions.

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- Bäcklund transformations and defects
- Solitons and defects
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From a physicist's perspective - began with Skyrme (1959-62).

$$\frac{1}{c^2}\frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = -\frac{m^2}{\beta}\sin\beta u.$$

- c is a constant with the dimensions of velocity (usually set to unity),
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- it is (almost) the simplest (a single scalar field), relativistic, integrable nonlinear wave equation in two dimensions (one time, one space) (*t*, *x*);
- it is simple enough to allow direct computations in the classical or quantum domains;
- it is complicated enough to display a wide range of interesting phenomena;
- though originally studied on the range -∞ < x < ∞, or on a circle (periodic boundary conditions), there are new features when the model is restricted to a half-line (x < 0, say), or to an interval (x ∈ [-L, L]), by suitable boundary conditions, or if there are 'impurities' or 'defects'.

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$$\frac{1}{c^2}\frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = -m^2 u +$$

$$+ \frac{m^2\beta^2}{3!} u^3 - \frac{m^2\beta^4}{5!} u^5 + \dots$$

The first three (linear) terms taken alone are simply the Klein-Gordon equation for a relativistic scalar particle with mass parameter *m*.

From a perturbative quantum field theory perspective it looks unexceptional until one starts to calculate - and finds that particle production is disallowed.

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$$\mathcal{L} = rac{1}{2} \partial_{\mu} u \, \partial^{\mu} u - rac{m^2}{\beta^2} (1 - \cos \beta u).$$

The corresponding conserved energy and momentum are given by

$$\mathcal{E} = \int_{-\infty}^{\infty} dx \, \left(\frac{1}{2} (u_t^2 + u_x^2) + \frac{m^2}{\beta^2} (1 - \cos \beta u) \right),$$

$$\mathcal{P}=-\int_{-\infty}^{\infty}dx\ u_tu_x.$$

Well-defined provided u is 'smooth' with $u_t, u_x \to 0, \ \beta u \to 2n\pi$, as $x \to \pm \infty$, where n is an integer or zero.

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It is easy to check that the following gives an exact (real) solution to the sine-Gordon equation:

$$e^{i\beta u/2} = \frac{1+iE}{1-iE}, \quad E = e^{ax+bt+c},$$

where a, b are real constants satisfying

$$a^2-b^2=m^2,$$

and *c* is a constant that need not be real, but *e^c* is real. Note:

- Useful to put a = m cosh θ, b = -m sinh θ; and θ is the 'rapidity'.
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Properties

Assume first E > 0 (ie $e^c > 0$).

• The spatial derivative u_x is given by

$$u_x = \frac{4a}{\beta} \frac{E}{1+E^2},$$

which implies u is monotonically increasing.

- As $x \to -\infty$, $e^{i\beta u/2} \to 1$; thus $u \to 0$ is a suitable choice for $x \to -\infty$.
- As $x \to +\infty$, $e^{i\beta u/2} \to -1$; since *u* is always increasing we must have $u \to 2\pi/\beta$ for $x \to +\infty$.

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A soliton snapshot



The lower curve represents u_x (and is similar in general shape to the energy density) and the upper curve represents the soliton itself smoothly interpolating u = 0 to $u = 2\pi$.

The solution is changing rapidly within a small region in the neighbourhood of x = 0.

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The solution is changing rapidly within a small region in the neighbourhood of x = 0.

- For θ > 0 the soliton is travelling along the *x*-axis in a positive direction with velocity b/a = tanh θ.
- Its energy and momentum are calculated directly to be

$$(\mathcal{E}, \mathcal{P}) = \frac{8m}{\beta^2}(\cosh\theta, \sinh\theta).$$

- Note: assigning the units of action (*ML*) to the action requires $[u]^2 = ML$ and hence $[\beta^2] = 1/ML$ (which is why a physicist might prefer not to put $\beta = 1$). Since [m] = 1/L, this means that *M* has the same dimensions as $\hbar m$, and it corresponds to a classically generated mass.
- A strongly localised field configuration \sim a particle.

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Return to the expression for a soliton:

$$e^{ieta u/2} = rac{1+iE}{1-iE}, \quad E = e^{ax+bt+c}$$

and replace *c* by $c + i\pi$ (equivalently, replace *E* by -E). Note

$$u_x = -\frac{4a}{\beta} \frac{E}{1+E^2},$$

which is always negative - this time the solution interpolates from 0 to -2π , with identical energy-momentum. Define a conserved ('topological') charge

$$Q=\frac{1}{2\pi}\int_{-\infty}^{\infty}dx\,u_x=\frac{1}{2\pi}[u(t,\infty)-u(t,-\infty)].$$

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Multi-solitons

It is also possible to check directly (use Maple/Mathematica) that the following expression is also a solution and describes two solitons (stems from the 60s - see any soliton book):

$$e^{i\beta u/2} = \frac{1+iE_1+iE_2-\Omega_{12}E_1E_2}{1-iE_1-iE_2-\Omega_{12}E_1E_2}, \ \ \Omega_{12} = \tanh^2\left(\frac{\theta_1-\theta_2}{2}\right),$$

where

$$E_k = e^{a_k x + b_k t + c_k}, \ a_k = m \cosh \theta_k, b_k = -m \sinh \theta_k, \ k = 1, 2$$

Also

$$(\mathcal{E}, \mathcal{P}) = (\mathcal{E}_1, \mathcal{P}_1) + (\mathcal{E}_2, \mathcal{P}_2),$$

the sum of the individual soliton energies and momenta.

Generalises to any number of solitons (point to note, rapidities are all different).

Multi-solitons

It is also possible to check directly (use Maple/Mathematica) that the following expression is also a solution and describes two solitons (stems from the 60s - see any soliton book):

$$e^{i\beta u/2} = \frac{1+iE_1+iE_2-\Omega_{12}E_1E_2}{1-iE_1-iE_2-\Omega_{12}E_1E_2}, \ \ \Omega_{12} = \tanh^2\left(\frac{\theta_1-\theta_2}{2}\right),$$

where

$$E_k = e^{a_k x + b_k t + c_k}, \ a_k = m \cosh \theta_k, b_k = -m \sinh \theta_k, \ k = 1, 2$$

Also

$$(\mathcal{E},\mathcal{P})=(\mathcal{E}_1,\mathcal{P}_1)+(\mathcal{E}_2,\mathcal{P}_2),$$

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Again, u_x is positive and, taking as example $\theta_1 = 0$, $\theta_2 = 0.5$, two maxima are clearly seen in the regions where the solution is changing rapidly:



In this snapshot the moving soliton is to the left of the stationary one (and the red curve represents sin(u/2)). Since the derivative is always positive, *u* increases from $0 \rightarrow 4\pi$.

Remarks:

- Either *E*₁ or *E*₂ or both can be replaced by −*E*₁, −*E*₂, respectively, to give solutions with soliton-anti-soliton, or two solitons.
- A simple time-periodic solution (known as a 'breather') may be constructed by setting

$$\theta_1 = i\lambda, \ \theta_2 = -i\lambda, \ c_1 = c_2.$$

• The energy-momentum of this breather is given by

$$(\mathcal{E},\mathcal{P})=rac{16m}{eta^2}(\cos\lambda,0)\equiv 2M(\cos\lambda,0).$$

Evidently, the energy of a breather is less than the mass of two solitons, indicating a bound-state - further evidence for Skyrme that this was an interesting model to analyse.

- A 'real' version of sine-Gordon is sinh-Gordon $\partial^2 u = -\sinh u$; it is at first sight less interesting because it has no real solitons.
- It is sometimes convenient to use light-cone variables $z = t + x, \overline{z} = t x$. Then the sinh-Gordon equation reads $4\partial \overline{\partial} u = -\sinh u$.
- The Liouville equation is simpler-looking: $4\partial \bar{\partial} u = -e^{u}$. It is also conformally invariant under the transformation

$$z \to z'(z), \ \bar{z} \to \bar{z}'(\bar{z}), \ u' = u + \ln\left(\frac{d\bar{z}'}{d\bar{z}}\frac{dz'}{dz}\right)$$

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Affine Toda field theory

The sinh/sine-Gordon model is the simplest of a large class of field theories based on Lie algebra data (the sinh/sine-Gordon model is based on the roots of a_1 or su(2)).

In many respects the whole class may be considered together though the sinh/sine-Gordon model is particularly special - they are all integrable in a sense that generalises Liouville's theorem for finite dynamical systems (meaning there are 'enough' conserved quantities in involution).

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Return for a while to the sine-Gordon equation we began with

$$\frac{1}{c^2}\frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = -\frac{m^2}{\beta}\sin\beta u,$$

or, alternatively, scaling away all constants, $u_{tt} - u_{xx} = -\sin u$.

A remarkable observation of Bäcklund (1882) concerns two solutions to the sine-Gordon equation related by first order differential equations:

$$u_{x} = v_{t} + \lambda \sin\left(\frac{u+v}{2}\right) + \lambda^{-1} \sin\left(\frac{u-v}{2}\right)$$
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The first interesting remark concerns the choice v = 0. With this choice *u* satisfies:

$$\begin{aligned} u_x &= \left(\lambda + \lambda^{-1}\right) \sin\left(\frac{u}{2}\right) \\ u_t &= \left(\lambda - \lambda^{-1}\right) \sin\left(\frac{u}{2}\right), \end{aligned}$$

whose solution is precisely the single soliton we had at the beginning provided we identify $\lambda = e^{\theta}$, where θ is the soliton's rapidity.

That is, *u* is given by

$$e^{iu/2} = rac{1+iE}{1-iE}, \quad E = e^{ax+bt+c},$$

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with $a = \cosh \theta$, $b = -\sinh \theta$.

The second point concerns energy and momentum, which are each clearly seen to be boundary terms. For example:

$$\mathcal{P} = -\int_{-\infty}^{\infty} dx \, u_t u_x = -\int_{-\infty}^{\infty} dx \left(\lambda - \lambda^{-1}\right) \sin\left(\frac{u}{2}\right) \, u_x.$$

Hence,

$$\mathcal{P} = \left(\lambda - \lambda^{-1}\right) \left[\cos\left(\frac{u}{2}\right)\right]_{-\infty}^{\infty} = -4\sinh\theta.$$

A similar argument yields the energy as a boundary contribtion

$$\mathcal{E} = -\left(\lambda + \lambda^{-1}\right) \left[\cos\left(\frac{u}{2}\right)\right]_{-\infty}^{\infty} = 4\cosh\theta.$$

It was also noted that the Bäcklund transformation can be used to generate multiple solitons. For example, taking v be a single soliton and solving for u leads to a double-soliton.

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Typical shock (or bore) in fluid mechanics:

- flow flips from supersonic to subsonic,
- abrupt change of depth in a channel.
 - Velocity field changes rapidly over a small distance,
 - Model by a discontinuity in **v**(**x**, *t*),
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An almost physical example - a defect or shock

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$$u(x,t)$$
 x_0 $v(x,t)$

$$\partial^2 u = -\frac{\partial U}{\partial u}, \quad x < 0, \quad \partial^2 v = -\frac{\partial V}{\partial v}, \quad x > 0$$

• How can the fields be 'sewn' together preserving integrability? One natural choice (δ -impurity) would be to put

$$u(0,t) = v(0,t), \quad u_x(0,t) - v_x(0,t) = \mu u(0,t),$$

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Consider the field contributions to momentum:

$$\mathcal{P}=-\int_{-\infty}^{0}dx\,u_{t}u_{x}-\int_{-\infty}^{0}dx\,v_{t}v_{x}.$$

Then, using the field equations, $2\dot{\mathcal{P}}$ is given by

$$= -\int_{-\infty}^{0} dx \left[u_{t}^{2} + u_{x}^{2} - 2U(u) \right]_{x} - \int_{0}^{\infty} dx \left[v_{t}^{2} + v_{x}^{2} - 2V(v) \right]_{x}$$

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$$= -2 \frac{d\Omega}{dt}$$

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$$\dot{\mathcal{E}} = [U_X U_t]_0 - [V_X V_t]_0.$$

Setting $u_x = v_t + X(u, v)$, $v_x = u_t + Y(u, v)$ we find

$$\dot{\mathcal{E}} = u_t X - v_t Y.$$

This is a total time derivative provided

$$X = -\frac{\partial D}{\partial u}, \quad Y = \frac{\partial D}{\partial v},$$

for some D. Then



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for some *D*. Then

$$\dot{\mathcal{E}} = -\frac{dD}{dt}.$$

Next, consider the energy density and calculate

$$\dot{\mathcal{E}} = [u_x u_t]_0 - [v_x v_t]_0.$$

Setting $u_x = v_t + X(u, v)$, $v_x = u_t + Y(u, v)$ we find

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This argument suggests sewing conditions of the form

$$u_x = v_t - \frac{\partial D}{\partial u}, \quad v_x = u_t + \frac{\partial D}{\partial v},$$

where *D* depends on both fields evaluated at x = 0, leading to

$$\dot{\mathcal{P}} = \mathbf{v}_t \frac{\partial D}{\partial u} + u_t \frac{\partial D}{\partial \mathbf{v}} - \frac{1}{2} \left(\frac{\partial D}{\partial u} \right)^2 + \frac{1}{2} \left(\frac{\partial D}{\partial \mathbf{v}} \right)^2 + (U - V).$$

This is a total time derivative provided the first piece is a perfect differential and the second piece vanishes. Thus....

$$\frac{\partial D}{\partial u} = -\frac{\partial \Omega}{\partial v}, \quad \frac{\partial D}{\partial v} = -\frac{\partial \Omega}{\partial u}.$$

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Exercise Investigate the possible combinations U, V, D.

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For example, $U(u) = m^2 u^2/2$, $V(v) = m^2 v^2/2$, D turns out to be

$$D(u,v) = \frac{m\sigma}{4}(u+v)^2 + \frac{m}{4\sigma}(u-v)^2,$$

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$$\mathcal{L} = \theta(-x)\mathcal{L}(u) + \delta(x)\left(\frac{uv_t - u_tv}{2} - D(u, v)\right) + \theta(x)\mathcal{L}(v)$$

The usual E-L equations provide both the field equations for u, v in their respective domains **and** the 'sewing' conditions.

Exercise in the free case, what happens to a wave incident from (say) the left half-line?

Show that if

$$u = \left(e^{ikx} + Re^{-ikx}\right)e^{-i\omega t}, \ v = Te^{ikx}e^{-i\omega t}, \ \omega^2 = k^2 + m^2,$$

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Choosing u, v to be sine-Gordon fields (and scaling the coupling and mass parameters to unity), we take:

$$D(u, v) = 2\left(\sigma \cos \frac{u+v}{2} + \sigma^{-1} \cos \frac{u-v}{2}\right)$$

to find

$$\begin{aligned} x &< x_0: \quad \partial^2 u &= -\sin u, \\ x &> x_0: \quad \partial^2 v &= -\sin v, \\ x &= x_0: \quad u_x &= v_t - \sigma \sin \frac{u+v}{2} - \sigma^{-1} \sin \frac{u-v}{2}, \\ x &= x_0: \quad v_x &= u_t + \sigma \sin \frac{u+v}{2} - \sigma^{-1} \sin \frac{u-v}{2}. \end{aligned}$$

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Solitons and defects

Consider a soliton incident from x < 0.

It will not be possible to satisfy the sewing conditions (in general) unless a similar soliton emerges into the region x > 0:

$$e^{iu/2} = \frac{1+iE}{1-iE}, \ e^{iv/2} = \frac{1+izE}{1-izE}, \ E = e^{ax+bt+c}, \ a = \cosh\theta, \ b = -\sinh\theta,$$

where z is to be determined. It is also useful to set $\lambda = e^{-\eta}$. • We find

$$z = \operatorname{coth}\left(\frac{\eta - \theta}{2}\right)$$

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η < θ implies z < 0; ie the soliton emerges as an anti-soliton.
The final state will contain a discontinuity of magnitude 4π at x = 0.

- $\eta = \theta$ implies $z = \infty$ and there is **no** emerging soliton.
- The energy-momentum of the soliton is captured by the 'defect'.

- The eventual configuration will have a discontinuity of magnitude 2π at x = 0.

• $\eta > \theta$ implies z > 0; ie the soliton retains its character.

Thus, the 'defect' or 'shock' can be seen as a new feature within the sine-Gordon model.

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- $\eta > \theta$ implies z > 0; ie the soliton retains its character.

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Thus, the 'defect' or 'shock' can be seen as a new feature within the sine-Gordon model.

• The shock is local so there could be several shocks located at $x = x_1 < x_2 < x_3 < \cdots < x_n$; these behave independently as far as a soliton is concerned, each contributing a factor z_i for a total 'delay' of $z = z_1 z_2 \dots z_n$.

• When several solitons pass a defect each component is affected separately.

- This means that at most one of them can be 'filtered out' (since the components of a multisoliton in the sine-Gordon model must have different rapidities).

• Since a soliton can be absorbed, can a starting configuration with u = 0, $v = 2\pi$ decay into a soliton?

 No, there is no way to tell the time at which the decay would occur (and quantum mechanics would be needed to provide the probability of decay as a function of time).

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• What about the other Toda field theories?

- They all have solitons, but they are not known to have Bäcklund transformations of the above type; can they nevertheless support defects?

- Not known.
- What about the Tzitzéica equation?

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The classical type II defect

Consider two relativistic field theories with fields *u* and *v*, and add a new degree of freedom $\lambda(t)$ at the defect location:

$$\mathcal{L} = \theta(-x)\mathcal{L}_{u} + \theta(x)\mathcal{L}_{v} + \delta(x)\left(2q\lambda_{t} - D(\lambda, p, q)\right)$$

where

$$q = \frac{u-v}{2}\Big|_0 \qquad p = \frac{u+v}{2}\Big|_0$$

Then the usual steps lead to

• equations of motion:

$$\partial^2 u = -U_u \quad x < 0 \qquad \partial^2 v = -V_v \quad x > 0$$

defect conditions at x = 0

$$2q_x = -D_p$$
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$$P=\int_{-\infty}^{0}dx\,u_{t}u_{x}+\int_{0}^{\infty}dx\,v_{t}v_{x},$$

and seek a functional $\Omega(u, v, \lambda)$ such that $P_t \equiv -\Omega_t$. Then $P + \Omega|_{x=0}$ is the total conserved momentum of the system. Constraints on U, V, Ω :

$$D_p = \Omega_\lambda$$
 $D_\lambda = \Omega_p$ $D_p D_q - \Omega_q D_\lambda = 2(U - V),$

implying

$$D = f(p + \lambda, q) + g(p - \lambda, q) \qquad \Omega = f(p + \lambda, q) - g(p - \lambda, q)$$
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$$f_{\lambda}g_q - g_{\lambda}f_q = (U - V) \leftrightarrow \{\Omega, D\} = (U - V)$$

- Exercise show that it is now possible to choose f, g in such a way that the potentials U, V can be any one of sine-Gordon, Liouville, Tzitzéica, or quadratic. Are there solutions other than the integrable cases?
- Remark In the sine-Gordon case the type-II defect is a new object in a sense it is a 'fused' pair of type-I defects (EC, Zambon, 2010). See also Weston 2010.

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Assume $\sigma > 0$ then..

- Expect Pure transmission compatible with the bulk S-matrix;
- Expect For each type of defect two different 'transmission' matrices (since the topological charge on a defect can only change by ±2 as a soliton/anti-soliton passes).
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$T^{b\beta}_{alpha}(heta,\eta)$

$a + \alpha = b + \beta$, $|\beta - \alpha| = 0, 2$, $a, b = \pm 1$, $\alpha, \beta \in \mathbb{Z}$



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 $S_{ab}^{cd}(\Theta) T_{d\alpha}^{f\beta}(\theta_{a}) T_{c\beta}^{e\gamma}(\theta_{b}) = T_{b\alpha}^{d\beta}(\theta_{b}) T_{a\beta}^{c\gamma}(\theta_{a}) S_{cd}^{ef}(\Theta)$

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With $\Theta = \theta_a - \theta_b$ and sums over the 'internal' indices β , *c*, *d*.

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Zamolodchikov's sine-Gordon S-matrix - reminder

$$S_{ab}^{cd}(\Theta) = \rho(\Theta) \begin{pmatrix} A & 0 & 0 & 0 \\ 0 & C & B & 0 \\ 0 & B & C & 0 \\ 0 & 0 & 0 & A \end{pmatrix}$$

where

$$A(\Theta) = \frac{qx_2}{x_1} - \frac{x_1}{qx_2}, \ B(\Theta) = \frac{x_1}{x_2} - \frac{x_2}{x_1}, \ C(\Theta) = q - \frac{1}{q}$$

and

$$\rho(\Theta) = \frac{\Gamma(1+z)\Gamma(1-\gamma-z)}{2\pi i} \prod_{1}^{\infty} R_k(\Theta) R_k(i\pi-\Theta)$$

$$R_k(\Theta) = \frac{\Gamma(2k\gamma+z)\Gamma(1+2k\gamma+z)}{\Gamma((2k+1)\gamma+z)\Gamma(1+(2k+1)\gamma+z)}, \ z = i\gamma/\pi.$$

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The Zamolodchikov S-matrix depends on the rapidity variables θ and the bulk coupling β via

$$x = e^{\gamma \theta}, \ q = e^{i\pi\gamma}, \ \gamma = \frac{8\pi}{\beta^2} - 1,$$

and it is also useful to define the variable

$$Q=e^{4\pi^2i/\beta^2}=\sqrt{-q}.$$

K-L solutions have the form

$$T^{b\beta}_{a\alpha}(\theta) = f(q, x) \begin{pmatrix} Q^{\alpha} \, \delta^{\beta}_{\alpha} & q^{-1/2} e^{\gamma(\theta - \eta)} \, \delta^{\beta - 2}_{\alpha} \\ q^{-1/2} \, e^{\gamma(\theta - \eta)} \, \delta^{\beta + 2}_{\alpha} & Q^{-\alpha} \, \delta^{\beta}_{\alpha} \end{pmatrix}$$

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....namely

$$\overline{f}(q, x) = f(q, qx)$$

$$f(q, x)f(q, qx) = \left(1 + e^{2\gamma(\theta - \eta)}\right)^{-1}$$

A slightly alternative discussion of these points is given in Bowcock, EC, Zambon, 2005, where most of the properties noted below are also described.

A 'minimal' solution has the following form

$$f(q,x) = \frac{e^{i\pi(1+\gamma)/4}}{1+ie^{\gamma(\theta-\eta)}} \frac{r(x)}{\overline{r}(x)},$$

where it is convenient to put $z=i\gamma(heta-\eta)/2\pi$ and

$$r(x) = \prod_{k=0}^{\infty} \frac{\Gamma(k\gamma + 1/4 - z)\Gamma((k+1)\gamma + 3/4 - z)}{\Gamma((k+1/2)\gamma + 1/4 - z)\Gamma((k+1/2)\gamma + 3/4 - z)}$$

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- η < 0 the off-diagonal entries dominate;
- $\theta > \eta > 0$ the off-diagonal entries dominate;
- η > θ > 0 the diagonal entries dominate;

 These are the same features we saw in the classical soliton-shock scattering.

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$$heta = \eta - rac{i\pi}{2\gamma} o \eta, \; eta o \mathsf{0}$$

$$T_{a\alpha}^{b\beta}(\theta) = f(q, x) \begin{pmatrix} Q^{\alpha} \, \delta_{\alpha}^{\beta} & q^{-1/2} e^{\gamma(\theta - \eta)} \, \delta_{\alpha}^{\beta - 2} \\ q^{-1/2} \, e^{\gamma(\theta - \eta)} \, \delta_{\alpha}^{\beta + 2} & Q^{-\alpha} \, \delta_{\alpha}^{\beta} \end{pmatrix}$$

- $\eta < 0$ the off-diagonal entries dominate;
- $\theta > \eta > 0$ the off-diagonal entries dominate;
- $\eta > \theta > 0$ the diagonal entries dominate;

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This pole is like a resonance, with complex energy,

 $E = m_s \cosh \theta = m_s (\cosh \eta \cos(\pi/2\gamma) - i \sinh \eta \sin(\pi/2\gamma))$ and a 'width' proportional to $\sin(\pi/2\gamma)$.

Using this pole and a bootstrap to define ^{odd} T leads to a non-unitary transmission matrix - interpret as the instability corresponding to the classical feature noted at $\theta = \eta$.

 The Zamolodchikov S-matrix has 'breather' poles corresponding to soliton-anti-soliton bound states at

$$\Theta = i\pi(1 - n/\gamma), \ n = 1, 2, ..., n_{\max};$$

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 $\delta(\mathbf{x})(\mathbf{u}\mathbf{v}_t - \mathbf{v}\mathbf{u}_t)$

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