# Integrable field theories with defects 

Ed Corrigan

Department of Mathematical Sciences, Durham University
Classical and Quantum Integrable Models
University of Kent

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Integrable dynamical systems and field theory have a long history (over 100 years) - with many developments since 1968

Integrable field theory in the presence of boundaries (one boundary or two), or defects (shocks), is more recent.

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From a physicist's perspective - began with Skyrme (1959-62).


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- it is complicated enough to display a wide range of interesting phenomena;
- though originally studied on the range $-\infty<x<\infty$, or on a circle (periodic boundary conditions), there are new features when the model is restricted to a half-line ( $x<0$, say), or to an interval ( $x \in[-L, L]$ ), by suitable boundary conditions, or if there are 'impurities' or 'defects'.

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The first three (linear) terms taken alone are simply the Klein-Gordon equation for a relativistic scalar particle with mass parameter m.

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## Properties

Assume first $E>0$ (ie $e^{c}>0$ ).

- The spatial derivative $u_{x}$ is given by

$$
u_{x}=\frac{4 a}{\beta} \frac{E}{1+E^{2}}
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which implies $u$ is monotonically increasing.

- As $x \rightarrow-\infty$, $e^{i \beta u / 2} \rightarrow 1$; thus $u \rightarrow 0$ is a suitable choice for $x \rightarrow-\infty$.
- As $x \rightarrow+\infty, e^{i \beta u / 2} \rightarrow-1$; since $u$ is always increasing we must have $u \rightarrow 2 \pi / \beta$ for $x \rightarrow+\infty$.


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## A soliton snapshot



The lower curve represents $u_{x}$ (and is similar in general shape to the energy density) and the upper curve represents the soliton itself smoothly interpolating $u=0$ to $u=2 \pi$.

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- For $\theta>0$ the soliton is travelling along the $x$-axis in a positive direction with velocity $b / a=\tanh \theta$. Its energy and momentum are calculated directly to be

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(\mathcal{E}, \mathcal{P})=\frac{8 m}{\beta^{2}}(\cosh \theta, \sinh \theta)
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## This expression is the energy-momentum of a relativistic particle $(c=1)$ of mass $M=8 m / \beta^{2}$.

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- Note: assigning the units of action $(M L)$ to the action requires $[u]^{2}=M L$ and hence $\left[\beta^{2}\right]=1 / M L$ (which is why a physicist might prefer not to put $\beta=1$ ). Since $[m]=1 / L$, this means that $M$ has the same dimensions as $\hbar m$, and it corresponds to a classically generated mass.
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- A strongly localised field configuration $\sim$ a particle.


## An anti-soliton

Return to the expression for a soliton:

$$
e^{i \beta u / 2}=\frac{1+i E}{1-i E}, \quad E=e^{a x+b t+c}
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and replace $c$ by $c+i \pi$ (equivalently, replace $E$ by $-E$ ). Note

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Then $Q=1$ for a soliton and $Q=-1$ for an anti-soliton.

## Multi-solitons

It is also possible to check directly (use Maple/Mathematica) that the following expression is also a solution and describes two solitons (stems from the 60s - see any soliton book):

$$
e^{i \beta u / 2}=\frac{1+i E_{1}+i E_{2}-\Omega_{12} E_{1} E_{2}}{1-i E_{1}-i E_{2}-\Omega_{12} E_{1} E_{2}}, \quad \Omega_{12}=\tanh ^{2}\left(\frac{\theta_{1}-\theta_{2}}{2}\right),
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where

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E_{k}=e^{a_{k} x+b_{k} t+c_{k}}, a_{k}=m \cosh \theta_{k}, b_{k}=-m \sinh \theta_{k}, \quad k=1,2
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the sum of the individual soliton energies and momenta.
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Generalises to any number of solitons (point to note, rapidities are all different).

Again, $u_{x}$ is positive and, taking as example $\theta_{1}=0, \theta_{2}=0.5$, two maxima are clearly seen in the regions where the solution is changing rapidly:


In this snapshot the moving soliton is to the left of the stationary one (and the red curve represents $\sin (u / 2)$ ). Since the derivative is always positive, $u$ increases from $0 \rightarrow 4 \pi$.

## Remarks:

- Either $E_{1}$ or $E_{2}$ or both can be replaced by $-E_{1},-E_{2}$, respectively, to give solutions with soliton-anti-soliton, or two solitons.
- A simple time-periodic solution (known as a 'breather') may be constructed by setting

$$
\theta_{1}=i \lambda, \quad \theta_{2}=-i \lambda, \quad c_{1}=c_{2}
$$

- The energy-momentum of this breather is given by

$$
(\mathcal{E}, \mathcal{P})=\frac{16 m}{\beta^{2}}(\cos \lambda, 0) \equiv 2 M(\cos \lambda, 0)
$$

Evidently, the energy of a breather is less than the mass of two solitons, indicating a bound-state - further evidence for Skyrme that this was an interesting model to analyse.

## Further remarks

- A 'real' version of sine-Gordon is sinh-Gordon $\partial^{2} u=-\sinh u$; it is at first sight less interesting because it has no real solitons.
It is sometimes convenient to use light-cone variables $z=t+x, \bar{z}=t-x$. Then the sinh-Gordon equation reads $4 \partial \partial u=-\sinh u$. also conformally invariant under the transformation


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- (Zamolodchikov) It can be useful to consider sinh/sine-Gordon as a perturbation of a conformal field theory.


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- (Zamolodchikov) It can be useful to consider sinh/sine-Gordon as a perturbation of a conformal field theory.


## Affine Toda field theory

The sinh/sine-Gordon model is the simplest of a large class of field theories based on Lie algebra data (the sinh/sine-Gordon model is based on the roots of $a_{1}$ or su(2)).

In many respects the whole class may be considered together though the sinh/sine-Gordon model is particularly special - they are all integrable in a sense that generalises Liouville's theorem for finite dynamical systems (meaning there are 'enough' conserved quantities in involution).
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## Bäcklund transformations

Return for a while to the sine-Gordon equation we began with

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\frac{1}{c^{2}} \frac{\partial^{2} u}{\partial t^{2}}-\frac{\partial^{2} u}{\partial x^{2}}=-\frac{m^{2}}{\beta} \sin \beta u
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or, alternatively, scaling away all constants, $u_{t t}-u_{x x}=-\sin u$.
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Eliminating $v$ gives the sine-Gordon equation for $u$, and vice-versa.

The first interesting remark concerns the choice $v=0$. With this choice $u$ satisfies:

$$
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& u_{x}=\left(\lambda+\lambda^{-1}\right) \sin \left(\frac{u}{2}\right) \\
& u_{t}=\left(\lambda-\lambda^{-1}\right) \sin \left(\frac{u}{2}\right)
\end{aligned}
$$

whose solution is precisely the single soliton we had at the beginning provided we identify $\lambda=e^{\theta}$, where $\theta$ is the soliton's rapidity.

That is, $u$ is given by

$$
e^{i u / 2}=\frac{1+i E}{1-i E}, \quad E=e^{a x+b t+c}
$$

with $a=\cosh \theta, b=-\sinh \theta$.

The second point concerns energy and momentum, which are each clearly seen to be boundary terms. For example:

$$
\mathcal{P}=-\int_{-\infty}^{\infty} d x u_{t} u_{x}=-\int_{-\infty}^{\infty} d x\left(\lambda-\lambda^{-1}\right) \sin \left(\frac{u}{2}\right) u_{x} .
$$

Hence,

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\mathcal{P}=\left(\lambda-\lambda^{-1}\right)\left[\cos \left(\frac{u}{2}\right)\right]_{-\infty}^{\infty}=-4 \sinh \theta .
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u(x, t) \quad x_{0} \quad v(x, t)
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Start with a single selected point on the $x$-axis, say $x=0$, and denote the field to the left of it $(x<0)$ by $u$, and to the right $(x>0)$ by $v$, with field equations in their respective domains:

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If there are 'sewing' conditions for which the last step is valid then $\mathcal{P}+\Omega$ will be conserved, with $\Omega$ a function of $u, v$ - and possibly derivatives - evaluated at $x=0$.

## Next, consider the energy density and calculate

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$$
\dot{\mathcal{E}}=-\frac{d D}{d t} .
$$

This argument suggests sewing conditions of the form

$$
u_{x}=v_{t}-\frac{\partial D}{\partial u}, \quad v_{x}=u_{t}+\frac{\partial D}{\partial v},
$$

where $D$ depends on both fields evaluated at $x=0$, leading to

$$
\dot{\mathcal{P}}=v_{t} \frac{\partial D}{\partial u}+u_{t} \frac{\partial D}{\partial v}-\frac{1}{2}\left(\frac{\partial D}{\partial u}\right)^{2}+\frac{1}{2}\left(\frac{\partial D}{\partial v}\right)^{2}+(U-V) .
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$$
\frac{\partial D}{\partial u}=-\frac{\partial \Omega}{\partial v}, \quad \frac{\partial D}{\partial v}=-\frac{\partial \Omega}{\partial u}
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In other words....

$$
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Show that if

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u=\left(e^{i k x}+R e^{-i k x}\right) e^{-i \omega t}, \quad v=T e^{i k x} e^{-i \omega t}, \quad \omega^{2}=k^{2}+m^{2}
$$

then $R=0$ and find $T$. (At first sight this seems surprising.)

## sine-Gordon

Choosing $u, v$ to be sine-Gordon fields (and scaling the coupling and mass parameters to unity), we take:

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D(u, v)=2\left(\sigma \cos \frac{u+v}{2}+\sigma^{-1} \cos \frac{u-v}{2}\right)
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to find

The last two expressions are a Bäcklund transformation frozen

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Comments and questions....

- The shock is local so there could be several shocks located at $x=x_{1}<x_{2}<x_{3}<\cdots<x_{n}$; these behave independently as far as a soliton is concerned, each contributing a factor $z_{i}$ for a total 'delay' of $z=z_{1} z_{2} \ldots z_{n}$.
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## The classical type II defect

Consider two relativistic field theories with fields $u$ and $v$, and add a new degree of freedom $\lambda(t)$ at the defect location:

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\mathcal{L}=\theta(-x) \mathcal{L}_{u}+\theta(x) \mathcal{L}_{V}+\delta(x)\left(2 q \lambda_{t}-D(\lambda, p, q)\right)
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where

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q=\left.\frac{u-v}{2}\right|_{0} \quad p=\left.\frac{u+v}{2}\right|_{0}
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Then the usual steps lead to

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\partial^{2} u=-U_{u} \quad x<0 \quad \partial^{2} v=-V_{v} \quad x>0
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As before, consider momentum

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P=\int_{-\infty}^{0} d x u_{t} u_{x}+\int_{0}^{\infty} d x v_{t} v_{x}
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and seek a functional $\Omega(u, v, \lambda)$ such that $P_{t} \equiv-\Omega_{t}$. Then
$P+\left.\Omega\right|_{x=0}$ is the total conserved momentum of the system.
Constraints on $U, V, \Omega$ :

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\begin{gathered}
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\end{gathered}
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- Curiousity: consider $\lambda$ and its conjugate momentum $\pi_{\lambda}=2 q$. Then, the Poisson bracket of the defect contributions to energy and momentum is related to the potential difference across the defect, that is

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- Remark In the sine-Gordon case the type-II defect is a new object - in a sense it is a 'fused' pair of type-I defects (EC, Zambon, 2010). See also Weston 2010.


## Shocks in sine-Gordon quantum field theory

## Assume $\sigma>0$ then...

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$$
S_{a b}^{c d}(\Theta) T_{d \alpha}^{f \beta}\left(\theta_{a}\right) T_{c \beta}^{e \gamma}\left(\theta_{b}\right)=T_{b \alpha}^{d \beta}\left(\theta_{b}\right) T_{a \beta}^{c \gamma}\left(\theta_{a}\right) S_{c d}^{e f}(\Theta)
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## Zamolodchikov's sine-Gordon S-matrix - reminder

$$
S_{a b}^{c d}(\Theta)=\rho(\Theta)\left(\begin{array}{cccc}
A & 0 & 0 & 0 \\
0 & C & B & 0 \\
0 & B & C & 0 \\
0 & 0 & 0 & A
\end{array}\right)
$$

where

$$
A(\Theta)=\frac{q x_{2}}{x_{1}}-\frac{x_{1}}{q x_{2}}, B(\Theta)=\frac{x_{1}}{x_{2}}-\frac{x_{2}}{x_{1}}, C(\Theta)=q-\frac{1}{q}
$$

and

$$
\begin{aligned}
\rho(\Theta) & =\frac{\Gamma(1+z) \Gamma(1-\gamma-z)}{2 \pi i} \prod_{1}^{\infty} R_{k}(\Theta) R_{k}(i \pi-\Theta) \\
R_{k}(\Theta) & =\frac{\Gamma(2 k \gamma+z) \Gamma(1+2 k \gamma+z)}{\Gamma((2 k+1) \gamma+z) \Gamma(1+(2 k+1) \gamma+z)}, z=i \gamma / \pi .
\end{aligned}
$$

The Zamolodchikov S-matrix depends on the rapidity variables $\theta$ and the bulk coupling $\beta$ via

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x=e^{\gamma \theta}, q=e^{i \pi \gamma}, \gamma=\frac{8 \pi}{\beta^{2}}-1
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Q=e^{4 \pi^{2} i / \beta^{2}}=\sqrt{-q}
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A slightly alternative discussion of these points is given in Bowcock, EC, Zambon, 2005, where most of the properties noted below are also described.

- A 'minimal' solution has the following form

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f(q, x)=\frac{e^{i \pi(1+\gamma) / 4}}{1+i e^{\gamma(\theta-\eta)}} \frac{r(x)}{\bar{r}(x)}
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where it is convenient to put $z=i \gamma(\theta-\eta) / 2 \pi$ and

$$
r(x)=\prod_{k=0}^{\infty} \frac{\Gamma(k \gamma+1 / 4-z) \Gamma((k+1) \gamma+3 / 4-z)}{\Gamma((k+1 / 2) \gamma+1 / 4-z) \Gamma((k+1 / 2) \gamma+3 / 4-z)}
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- These are the same features we saw in the classical
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Remarks ( $\theta>0$ ): it is tempting to suppose $\eta$ (possibly renormalized) is the same parameter as in the classical model.

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- All this refers to type-I but recently a new solution has been found corresponding to type-II (EC, Zambon, 2010), and a new way of regarding both has been developed (Weston, 2010).

Further questions....

- Moving shocks can be constructed in sine-Gordon theory but their quantum scattering is not yet completely analysed, though there is a candidate S-matrix compatible with the soliton transmission matrix. (Bowcock, EC, Zambon, 2005; Weston, 2010)
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